

# CBCGS SCHEME

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15MT34

## Third Semester B.E. Degree Examination, Dec.2018/Jan.2019 Control Systems

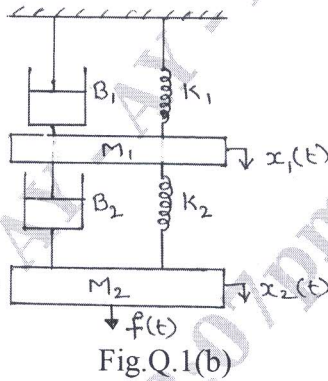
Time: 3 hrs.

Max. Marks: 80

- Note: 1. Answer any FIVE full questions, choosing one full question from each module.  
2. Write neat sketches wherever required.*

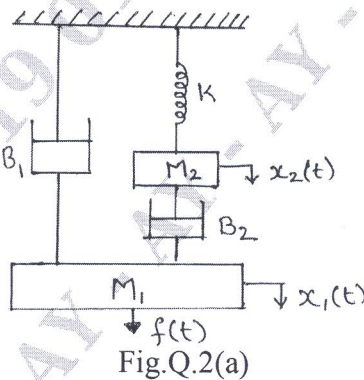
### Module-1

- 1 a. Explain with an example and block diagram, a closed loop control system. (06 Marks)
- b. Obtain the transfer function for the following mechanical system shown in Fig.Q.1(b). (10 Marks)



OR

- 2 a. For the given system shown in Fig.Q.2(a), write the differential equations in force voltage and force-current analogy. (06 Marks)



- b. Reduce the block diagram shown in Fig.Q.2(b) by reduction technique and find  $C(s)/R(s)$ . (10 Marks)

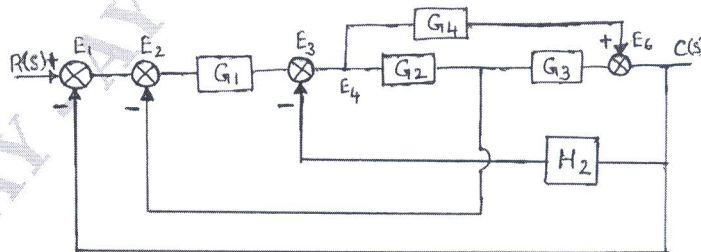


Fig.Q.2(b)

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.  
2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.

Module-2

- 3 a. Using SFG technique, find the transfer function for the system shown in Fig.Q.3(a). (08 Marks)

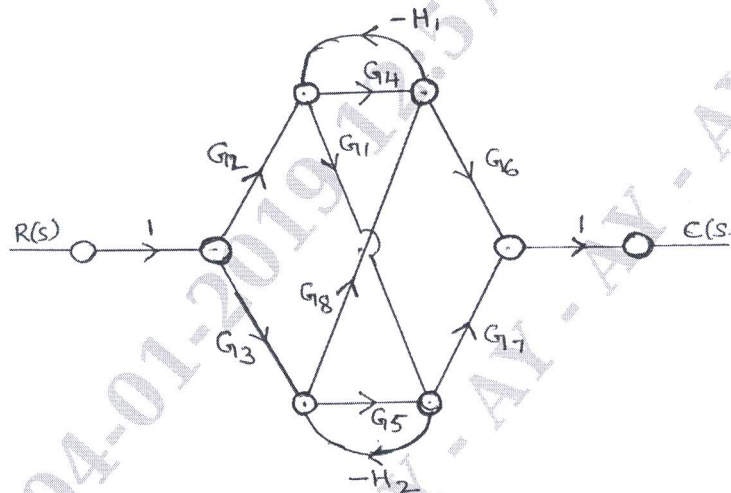


Fig.Q.3(a)

- b. For the Fig.Q.2(b), find the transfer function using Mason's Gain formula. (08 Marks)

OR

- 4 a. Derive an expression for a second order system subjected to an unit step input for an underdamped system. (09 Marks)
- b. For a system with  $G(s)H(s) = \frac{K}{s^2(s+3)(s+4)}$ , find the value of K for which the steady state error is to be limited to 12 when the input is  $1 + 12t + \frac{50}{2} t^2$ . (07 Marks)

Module-3

- 5 a. For an unity feed back system, the system is conditionally stable and oscillates with a frequency of 6 rad/sec. Find  $K_{mar}$  and R,  $G(S) = \frac{9}{S^3 + RS^2 + 3KS}$ . (06 Marks)
- b. The characteristic equation of the system is  $s^6 + 4s^5 + 3s^4 - 16s^2 - 64s - 48 = 0$ . Check the stability of the equation using RH criteria and find the roots and W. (10 Marks)

OR

- 6 Sketch the Root locus for the given transfer function  $G(S)H(S) = \frac{K}{s(s^2 + 4s + 10)}$ . Comment on the stability of the system. (16 Marks)

Module-4

- 7 Sketch the Bode plot for the given transfer function with  $G(s)H(s) = \frac{10(1+0.5s)}{S(1+0.1s)(1+0.2s)}$ . Find  $w_{gc}$ ,  $w_{pc}$ , GM and PM. Comment on its stability. (16 Marks)

OR

- 8 Sketch the Nyquist plot for  $G(s)H(s) = \frac{K}{s^4 + 8s^3 + 17s^2 + 10s}$ . Find the value of K for the system to be conditionally stable. (16 Marks)

**Module-5**

- 9 a. Obtain the state model of the electrical network shown in Fig.Q.9(a) in the standard form. Given  $t = t_0$ ,  $i(t) = i(t_0)$  and  $v_0(t) = v_0(t_0)$ . (08 Marks)

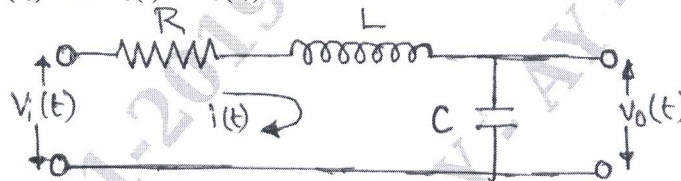


Fig.Q.9(a)

- b. Consider a system having state model

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -2 & -3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 3 \\ 5 \end{bmatrix} u \quad \text{and} \quad Y = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad \text{with } D = 0. \quad \text{Obtain its transfer function.} \quad (08 \text{ Marks})$$

OR

- 10 a. Obtain the complete time response of the system given by  $\dot{x}(t) = \begin{bmatrix} 0 & 1 \\ -2 & 0 \end{bmatrix} x(t)$  where  $x(0) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $Y(t) = \begin{bmatrix} 1 & -1 \end{bmatrix} x(t)$ . (10 Marks)

- b. Find the state transition matrix of the state equation  $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} U$  using the inverse transform method. (06 Marks)

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